



Typhoon HIL

4th Generation HIL.



HIL606.

Speed, power and flexibility.
Together as one.

Cal Power

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HIL606

The 4th Generation flagship has arrived.

Robustness meets speed with future-proof connectivity options.

Approach physical tests of your control system with confidence. With the speed of our latest 4th generation devices, together with the power of our 6-series, 8-core processors, you can control more high-fidelity models than

ever before. And with new unique connectivity options, your controller won't know the difference between your test models and the devices in the field, no matter your use case.

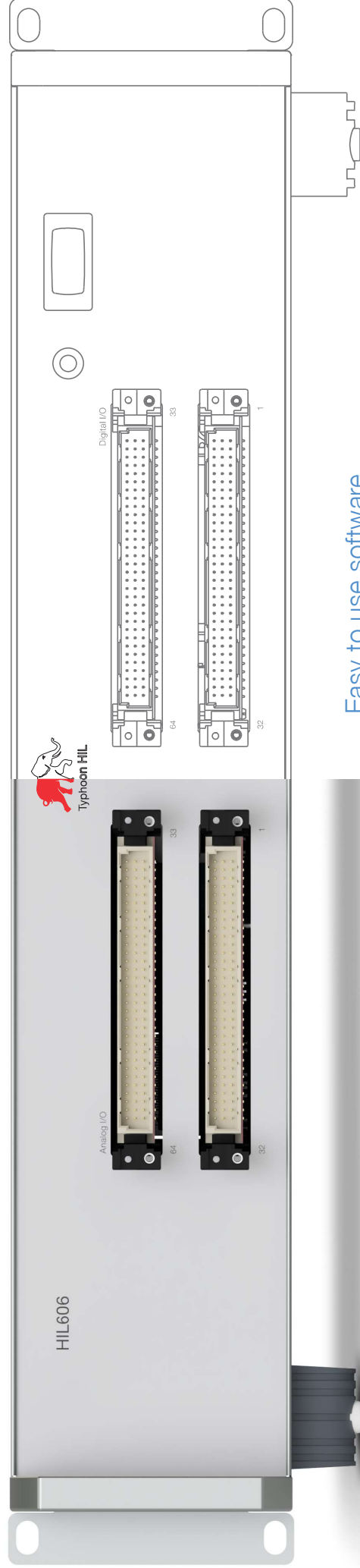
What's new?

- Upgrade in a flash with backwards compatibility for all devices and pin-to-pin compatibility with HIL604
- Model converters at timesteps as fast as 200 ns
- Down to 200 ns Analog Output update rate
- 3.5 ns Gate Drive System (GDS) Oversampling on all Digital Inputs
- Simulate your full microgrid with capacity for up to 24 Average Converter models
- Built-in M.2 slot for long-term data storage
- Unparalleled connectivity options:
 - o 6 Ethernet ports, including 2 EtherCAT ports
 - o 4 CAN ports, including 2 ports for flexible data rates (CAN FD)
 - o 2 Quad-SFP (QSFP) ports



Visit Typhoon HIL HIL606 website page.

Now you have the **speed** you love from our latest 4th generation devices together with the **power** of our 6-series, 8-core processors, balanced with the **flexibility** you require to connect to the devices you need.



Easy to use software toolchain.

Together with Typhoon HIL's easy to use software toolchain and top of the line support, you have the tools you need to perform rapid

control prototyping with sophisticated real-time test scenarios from the comfort of the office, no matter your experience level.

0.2 μ s	3.5 ns	24 (3PH)*	16/8 (1PH/3PH)*	16 units
Min. Simulation Step	DI Sampling Resolution	Detailed DER Models	Detailed Converter Models	Paralleling

*per HIL unit

Speed

for modeling and testing fast-switching converters.

SCADA demonstration of an EV/DC Charger example running on a single HiL606 at 250ms timestep

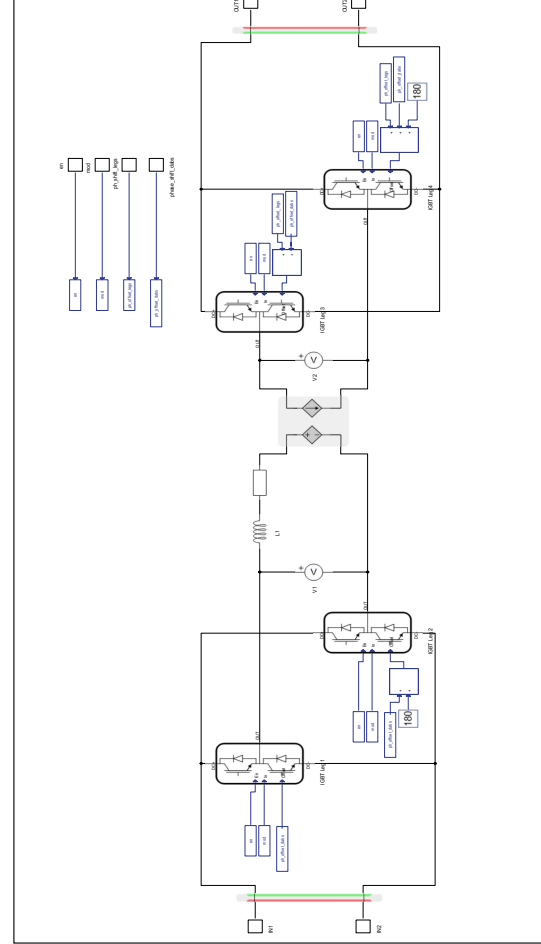
Learn more on Typhoon HIL e-Mobility website page.



“ Early porting of the controller algorithm to the real hardware solves a large number of issues prior to system integration. This results in significant development time and cost savings. [Read more:](#) ”



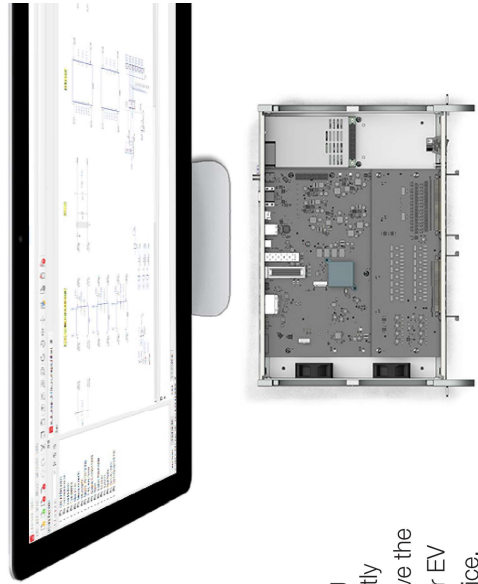
Dr. Roland Greul
Manager of Department at AVL



The model above represents of 1 of 3 DC/DC high frequency isolation stages of the featured EV DC charging example, using 3 Dual Active Bridge (DAB) converters in parallel.

Need to model several dual-active bridges together at the highest switching frequencies?

With the HiL606, you can test many high-switching frequency complex converters with multi-module Si-C based converters between the 50 to 500 kHz range at once. With analog time resolution at 200 nanoseconds and greatly increased processing and IO capacity you have the tools you need to test your full electric drive or EV charging system in real-time with a single device.



Power

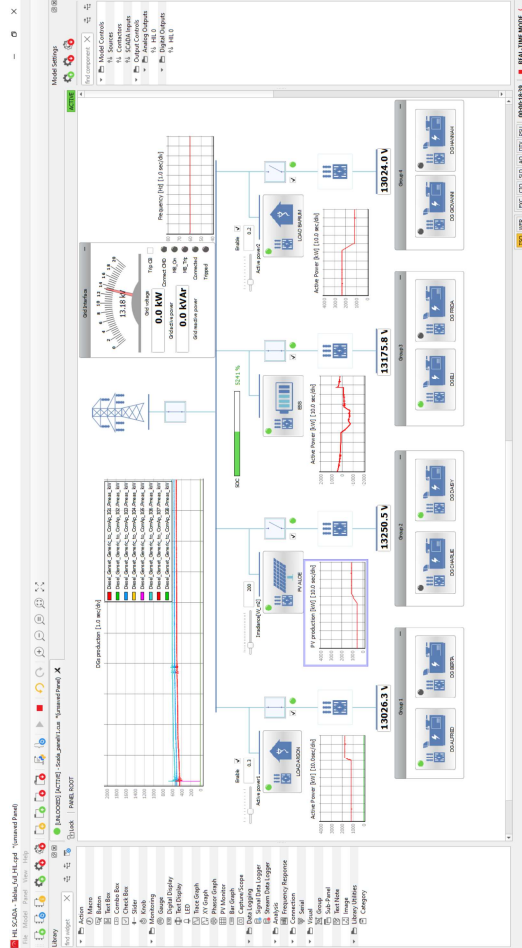
to run complex models at short timesteps.



Learn more on Typhoon HIL Microgrid website page.

Worried your microgrid models are too complex to integrate real hardware and low-level controllers in your test setup?

The HIL606 supports 24 average distributed energy resource (DER) models in real-time at once, and at very short timesteps. This means you are extremely well-equipped for simulating full microgrid models in real-time with real equipment at the highest level of detail.

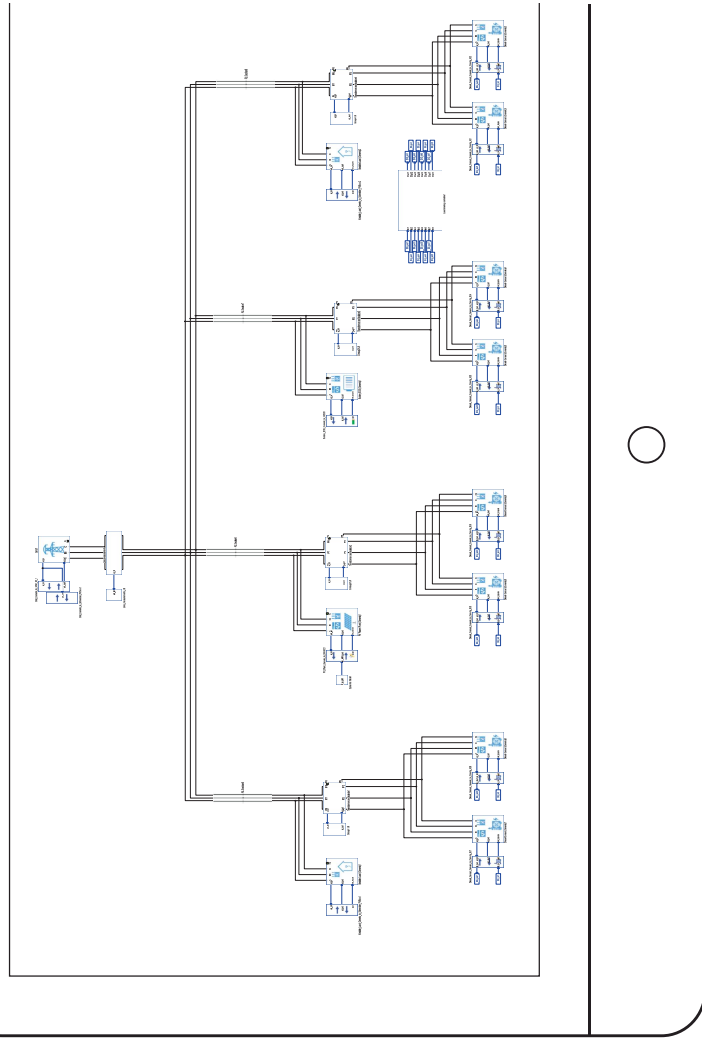


Read more:



We need a powerful real-time simulation platform in order to test our control system correctly.

David Dunnett
Head of Software Development
at Rolls-Royce Solutions



Example Rolls-Royce Solutions Berlin microgrid model setup for testing their mtu Microgrid Controller over Modbus TCP communication. This model uses only 4 of the HIL606's 8 available cores.

HIL SCADA demonstration of an islanded microgrid response to changes in DER production

Flexibility

to customize your testbed integration.

Flexibility to customize your CAN-testbed integration.
Best-in-class connectivity right out of the box.

Need flexible data rates for your CAN-connected vehicle components? Or just a faster response when connecting to third-party devices?

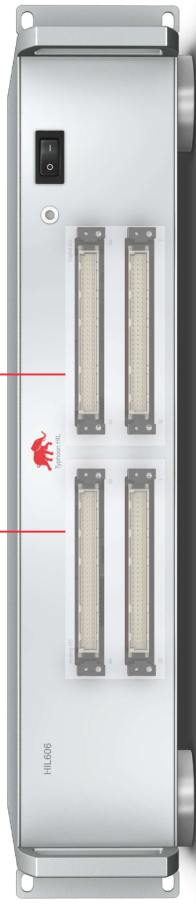
Now you can connect and use your HIL testbed with more flexibility than ever, thanks to completely new interfaces like EtherCat, CAN FD, and even an M.2 slot for long-term data storage. Expanded Quad Small Form-Factor Pluggable (QSFP) and Ethernet options give you strong support for low-level and time-critical internet-based protocols.

Analog I/O

- 32 Analog Inputs and 64 Analog Outputs
- 200 ns minimum sampling resolution

Digital I/O

- 64 Digital Inputs and 64 Digital Outputs
- 3.5 ns minimum oversampling resolution



M.2 slot inside

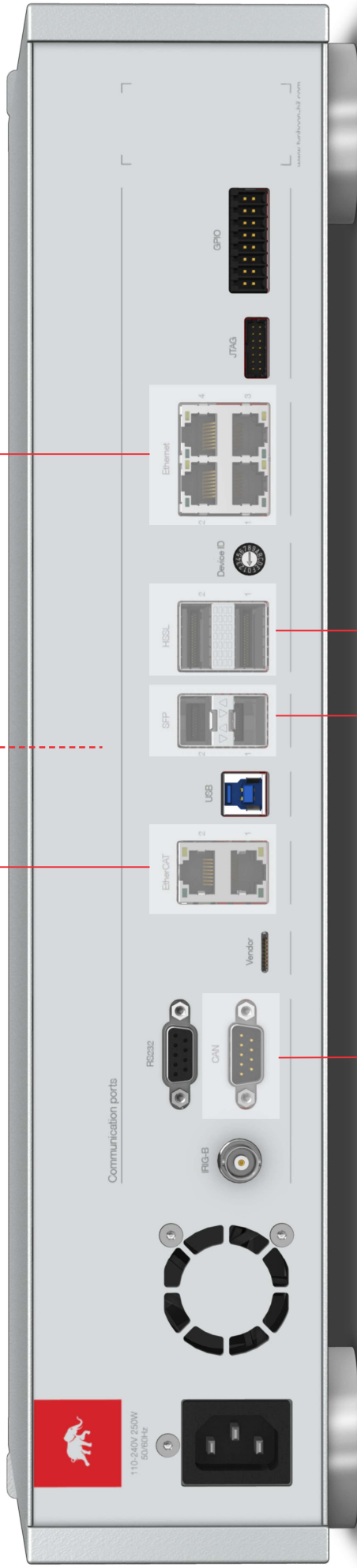
- Optional SSD for long-term offline data acquisition

4 Ethernet ports

- The first HIL device to have 4 Ethernet ports for greater flexibility to support multiple networks and different protocols.
- 2 ports for high level protocols
 - Modbus, DNP3, OPC UA
 - Including THOC communication
- 2 ports for time critical protocols
 - IEC 61850 SV, Ethernet VE

2 EtherCAT ports

- Hardware-supported slave interfaces
- Low latency daisy chaining with other EtherCAT devices



2 CAN + 2 CAN FD ports

- Double the connectivity options with CAN devices
- Full support for flexible data rates in CAN FD ports
- Ideal for e-Mobility

2 SFP ports

- Communication with other devices only
- SFP Simulation Link capable

2 QSFP for paralleling

- Connect 16 devices with more connection flexibility
- Bidirectional link
- Not required to close the ring

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Drive your tests faster than ever before.

E-mobility is fast, so its control systems must be faster. Testing performance requires criteria such as high dynamics, broad voltage ranges, and system stability despite rapidly changing loads and conditions.

The HIL606 was designed with these needs in mind. With timesteps as low as 200 nanoseconds and 3.5 nanoseconds digital oversampling resolution, MOSFET, IGBT

losses, and thermal losses can be modeled just as they would behave in the real device. Best of all, with Typhoon HIL's complete solution, you don't need 3rd party software tools at any stage of the V-curve development. Still, the HIL606 does play well with others: direct compatibility with a wide array of existing software and hardware solutions mean you can easily start using HIL where you need it most.



We decided to use the Typhoon HIL hardware-in-the-loop simulation platform to shorten development time.

Ryota Kitamoto
Engineer at Honda R&D



Read more:

main processor
FPGA



HIL606

75% faster



HIL604

co-processor
CPU



HIL606

10x faster



HIL604

Go wild with test cases.

Designing control systems for microgrids is a very delicate task. Controllers need to perform with a wide variety of devices and standards that continually evolve. Connected PV inverters can lose communication, even while the PV continues to inject energy into the grid.

With HIL, you have full control over the whole powerplant. You can test without any of the physical and safety constraints that come with real-world and power lab testing to see how the system responds in potentially catastrophic situations. You can address communication issues in advance by using the real protocols you will in the field. Powerful test automation tools make it easy to test as you develop.

In short, HIL606 lets you simulate more, faster.



Tilo Buehler
Global Product
Manager/Grid Edge
Solutions at Hitachi ABB

Read more:



analog and digital
IO



HIL606

2.5x faster



HIL604

model capacity
DER



HIL606

2.4x detailed 3rd models



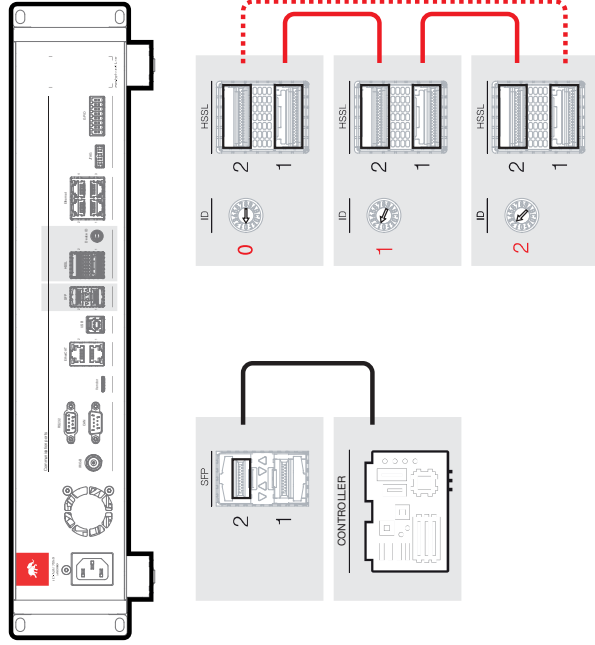
HIL604

Uncompromising performance.

Parallel your HILs.
Explode your potential.

Use the high-speed optical link to parallel your HIL606's while maintaining the small timestep. With the ability to parallel up to 16 units, you can model hundreds of detailed converter models in real-time without sacrificing model speed or model fidelity.

Easy connectivity options let you build a high performing P-HIL tested in a day. Just connect the optical link interface to any amplifier and start emulating your powertrain or full microgrid.



Four Small Form Factor Pluggable (SFP) ports:

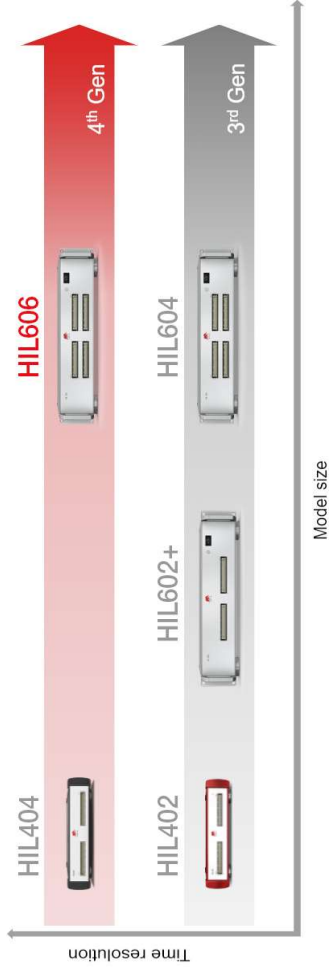
- All can be used for paralleling
- Two SFP ports allow for faster than ever paralleling capacity

I/O 16 64 256 ... and more!

HIL device comparison.



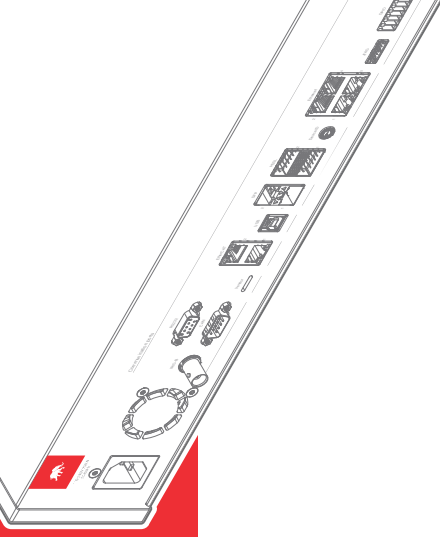
	HIL402	HIL404	HIL604	HIL606
Model capacity				
Detailed converter models (1ph / 3ph)	8 / 4	8 / 4	16/8	16/8
Average converter models (3ph)	8	12	10	24
Distribution network simulation	✓	✓	✓	✓
Time resolution				
Minimal simulation step	500 ns	200 ns	500 ns	200 ns
DI sampling resolution	6.2 ns	3.5 ns	6.2 ns	3.5 ns
IO				
Analog I/O per unit	16/16	16/16	32/64	32/64
Digital I/O per unit	32/32	32/32	64/64	64/64
Connectivity				
USB	✓	✓	✓	✓
Ethernet	✓	✓	✓	✓
CAN	✓	✓	✓	✓
RS232	✓	✓	✓	✓
EtherCAT				✓
SFP		✓		✓
Time synchronization (PPS and IRIG-B)			✓	✓
Paralleling		up to 4 units	up to 16 units	up to 16 units



HIL606 technical details.



For more technical details
read Typhoon HIL Hardware
documentation.

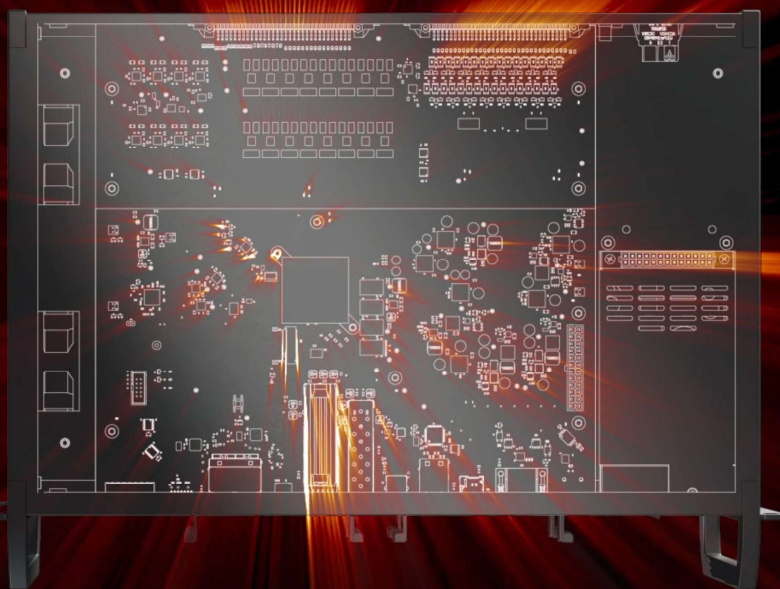


User Power Supply Stage (PSU)	±5 V analog ±12 V analog +3.3 V digital +5 V digital	up to 2 A, resettable protection up to 2 A, resettable protection up to 2 A, resettable protection up to 2 A, resettable protection
Digital inputs (DI)	Channels Input voltage range V_i Threshold voltages (low, high) Input resistance Protection DI sampling resolution	64 channels $-15 V < V_i < 15 V$ $(V_{iL}(\max) = 0.8 V; V_{iH}(\min) = 2 V)$ 10 k Ω ±24 V tolerant, ESD protection 3.5 ns
Digital outputs (DO)	Channels Output voltage range V_o Threshold voltages (low, high) Output resistance Protection	64 channels $0 V < V_o < 5 V$ $(V_{oL}(\max) = 0.2 V; V_{oH}(\min) = 4.8 V)$ 430 Ω ±24 V tolerant, ESD protection
Digital IO connector	Connector type	DIN 41612, type C 96 pin male connector
Connectivity	Ethernet USB 3.0 CAN FDCAN RS232 High speed serial link Quad SFP JTAG GPIO EtherCAT Time synchronization (IRIG-B)	4x RJ45 connectors; 10/100/1000 Mbps 1x type B connector 2x DE9 male Connector 2x DE9 male Connector DE9 Female Connector
Housing	Dimensions Weight	19" rack mountable; 2U height up to 10 kg
Power supply	Input voltage Power consumption	100 - 250 VAC up to 250 W

Processor	Processor configurations	ZU9EG Zynq UltraScale+ MPSoC up to 8 processing cores
Analog inputs (AI)	Channels Resolution Input Voltage Range: Sample Rate Linearity (DNL/INL) Gain error / Offset error Input Resistance Protection	32 16 bit ADC ±10 V up to 1 MSPS 1/2 0.01 % / 1 mV ~30 k Ω ±24 V tolerant, ESD protection
Analog Outputs (AO)	Channels Resolution Output Voltage Range Sample Rate Linearity (DNL/INL) Gain error / Offset error Output Resistance Protection	64 16 bit ADC ±10 V up to 5 MSPS 1/1 0.01 % / 1 mV ~0 Ω ±24 V tolerant, ESD protection
Analog IO connector	Connector	DIN 41612, type C 96 pin male connector



Typhoon HIL



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